

# Differentiation

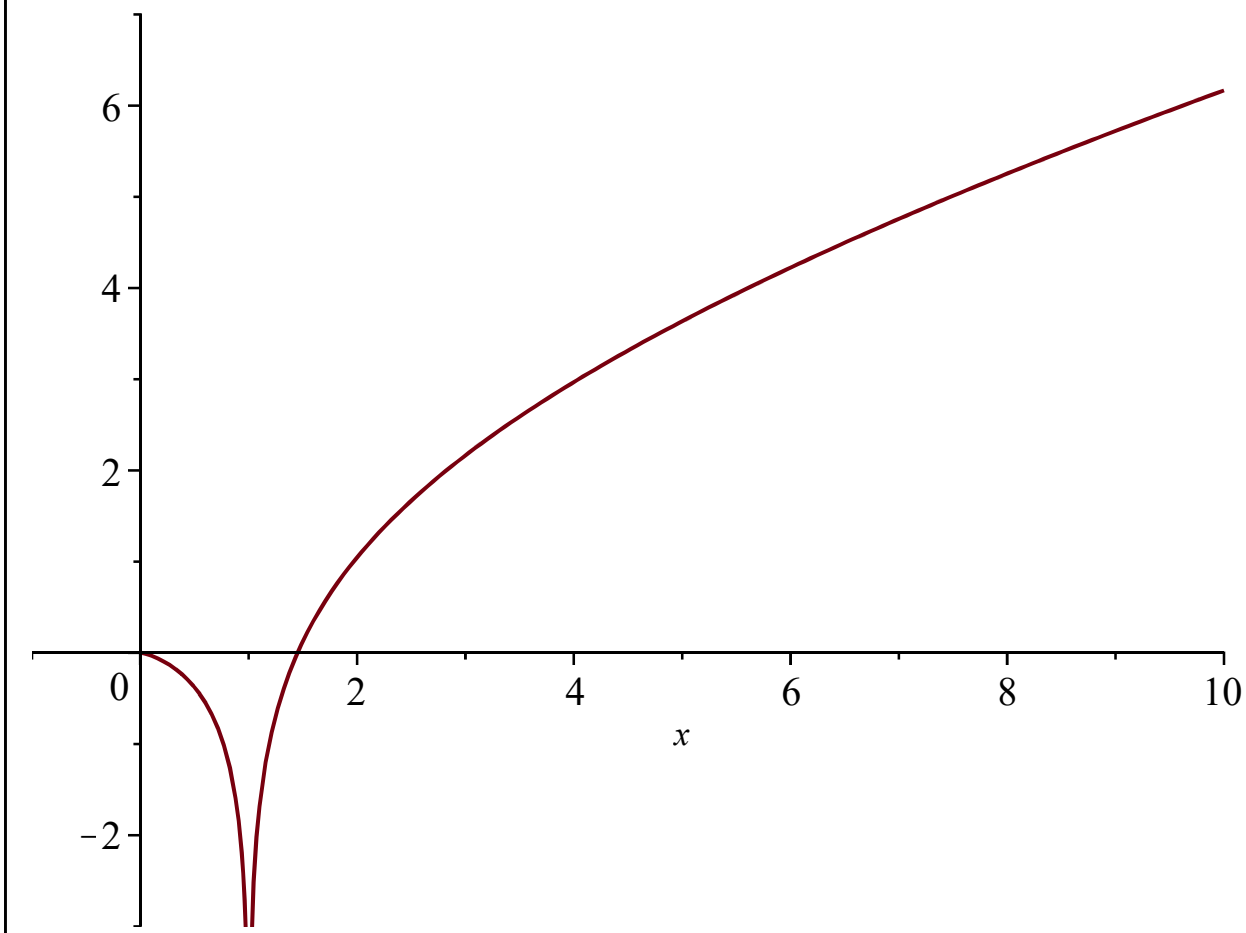
## Exercise 1

(a)

```
> q := sscanf("f*6#\ "xG6\"6#*CopyrightGF%-#ifG6%-%%typeG6$9$%)  
constantG-%&evalfG6#-%#LiG6#F.-.\ "qGF5F%F%F%", "%m") [1];  
q := proc(x) ... end proc
```

(1)

```
> plot(q(x), x=-1..10, -3..7);
```



The function is undefined for  $x < 0$ . It zero (and the graph is flat) at  $x = 0$ , then it drops down to  $-\infty$  at  $x = 1$ , then climbs back to zero at about  $x = 1.4$ , and increases thereafter towards  $\infty$ .

(b)

When  $x < 0$ , the function  $q'(x)$  is undefined (because  $q(x)$  is). We have  $q'(0) = 0$ , and then  $q'(x) < 0$  for  $0 < x < 1$  (because the graph is sloping downwards). The derivative is undefined again when  $x = 1$ , but  $q'(x) > 0$  for  $x > 1$  (because the graph is sloping upwards).

(c)

```
> Q := (x,h) -> (q(x+h)-q(x))/h;
```

(2)

$$Q := (x, h) \mapsto \frac{q(x+h) - q(x)}{h} \quad (2)$$

```
> e := exp(1);
```

$$e := e \quad (3)$$

```
> Digits := 30;
```

$$Digits := 30 \quad (4)$$

(d)

```
> Q(e^2, 0.01);
```

$$0.499830983358648545443169703000 \quad (5)$$

```
> Q(e^2, 0.0000001);
```

$$0.499999998308308974805400000000 \quad (6)$$

```
> Q(e^2, 10^(-10));
```

$$0.499999999998308309000000000000 \quad (7)$$

It is clear from this that  $q'(e^2) = \frac{1}{2}$ .

(e)

```
> Q(e^3, 10^(-10));
```

$$0.333333333333056738500000000000 \quad (8)$$

```
> Q(e^4, 10^(-10));
```

$$0.2499999999994276300000000000 \quad (9)$$

It is clear from this that  $q'(e^3) = \frac{1}{3}$  and  $q'(e^4) = \frac{1}{4}$ . We therefore guess that  $q'(e^t) = \frac{1}{t}$  for all  $t$ .

Moreover, given  $x > 0$ , we can write  $x = e^t$  with  $t = \ln(x)$ , so  $q'(x) = \frac{1}{\ln(x)}$ . This means that  $q(x)$  is

actually the same as a standard function called  $\text{Li}(x)$ , which is defined by  $\text{Li}(x) = \int_0^x \frac{1}{\ln(t)} dt$ ; you can

enter `?Li` for more information.

## Exercise 2

(a)

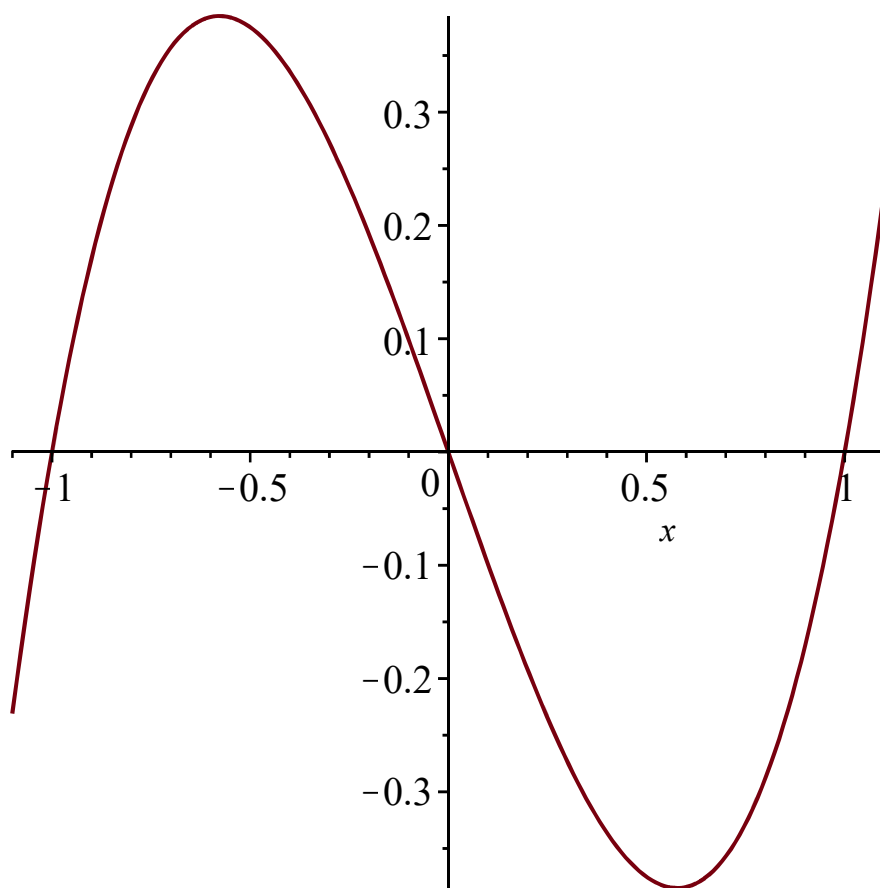
The roots of  $f'(x)$  occur where the graph of  $f(x)$  is flat, or in other words, the tangent line is horizontal. This occurs wherever  $f(x)$  has a local maximum or a local minimum (and possibly also in some other places, called inflexion points).

(b)

```
> f := (x) -> x^3 - x;
```

$$f := x \mapsto x^3 - x \quad (10)$$

```
> plot(f(x), x=-1.1..1.1);
```



There are roots of  $f(x)$  at  $x = -1$ ,  $x = 0$  and  $x = 1$ . Between  $x = -1$  and  $x = 0$  we have a root of  $f'(x)$  at about  $x = -0.6$ , corresponding to the top of the left-hand hump. Between  $x = 0$  and  $x = 1$  we have a root of  $f'(x)$  at about  $x = 0.6$ , corresponding to the top of the right-hand hump. Thus, Rolle's principle is satisfied.

```
> solve (f (x)=0, x) ;
```

$$0, 1, -1$$

(11)

```
> D (f) (x) ;
```

```
> solve (D (f) (x)=0, x) ;
```

$$3x^2 - 1$$

$$\frac{\sqrt{3}}{3}, -\frac{\sqrt{3}}{3}$$

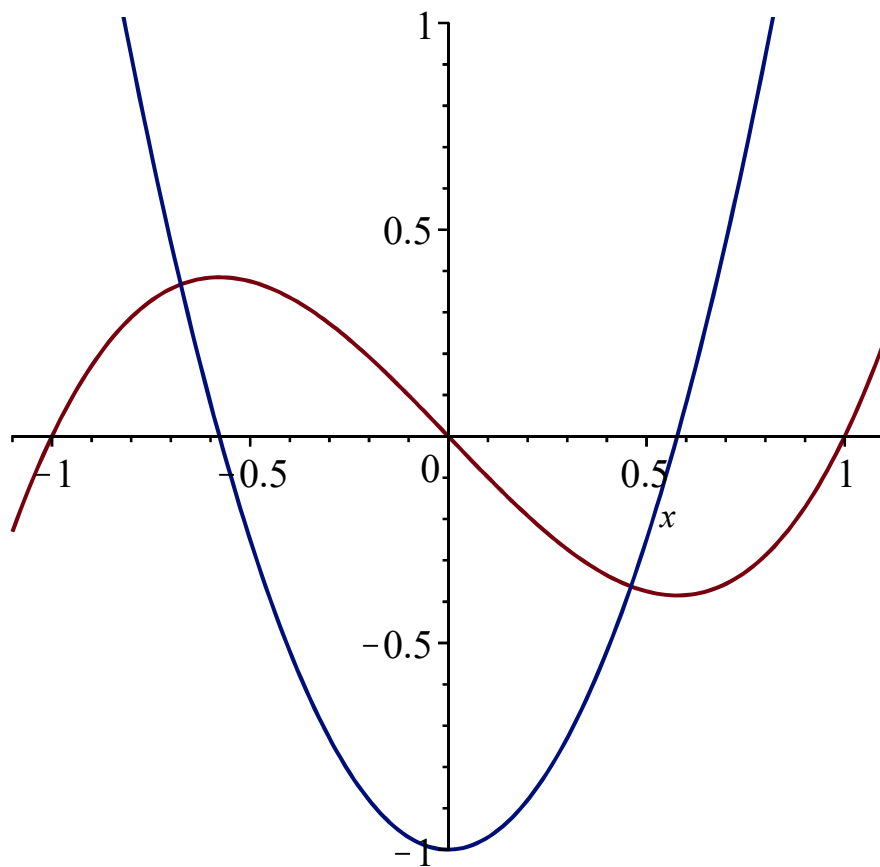
(12)

```
> 3*x^2-1;
```

$$3x^2 - 1$$

(13)

```
> plot ([f (x), D (f) (x)], x=-1.1..1.1, -1..1) ;
```



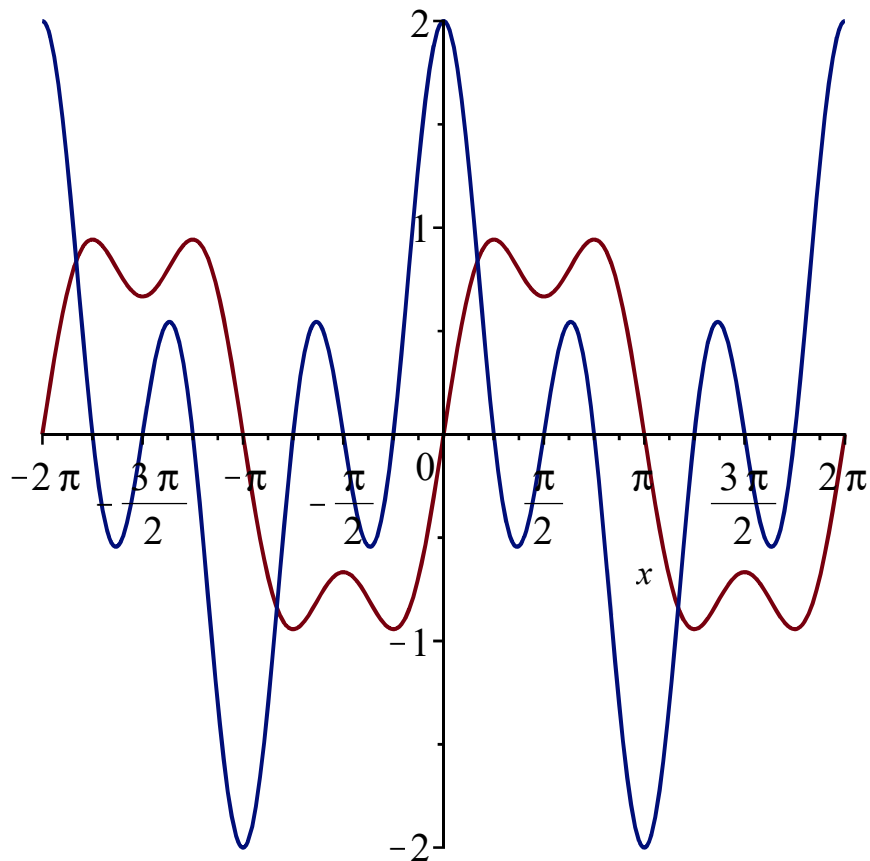
(c)

```
> g := (x) -> sin(x) + sin(3*x) / 3;
```

$$g := x \mapsto \sin(x) + \frac{\sin(3x)}{3}$$

(14)

```
> plot([g(x), D(g)(x)], x = -2*Pi .. 2*Pi);
```



We can see roots of  $g(x)$  at  $x = -2\pi$ ,  $-\pi$ ,  $0$ ,  $\pi$  and  $2\pi$ ; in general, the roots are at  $x = n\pi$  for integers  $n$ . Between  $x=0$  and  $x=\pi$  there are two maxima and one local minimum, giving three roots of  $g'(x)$ . (This is perfectly consistent with Rolle's principle, which says only that there is *at least one* root of  $g'(x)$  between  $0$  and  $\pi$ .) Similarly, between  $x=\pi$  and  $x=2\pi$  there are two minima and one local maximum for  $g(x)$ , corresponding to the three places where the graph of  $g'(x)$  (in green) crosses the  $x$ -axis. We can find the location of these roots as follows:

```
> solve(D(g)(x)=0,x);
```

$$\frac{\pi}{4}, \frac{3\pi}{4}, \frac{\pi}{2}$$
(15)

Maple has reported only the roots between  $0$  and  $\pi$ . We see from the graph that these roots can be shifted by any multiple of  $\pi$ , so the roots have the form  $n + \frac{\pi}{4}$  or  $n + \frac{3\pi}{4}$  or  $n + \frac{\pi}{2}$  for integers  $n$ .

(We can get Maple to produce this answer by setting `_EnvAllSolution:=true`; however, it reports the result in a convoluted and confusing form, so it is better to just inspect the graph.)

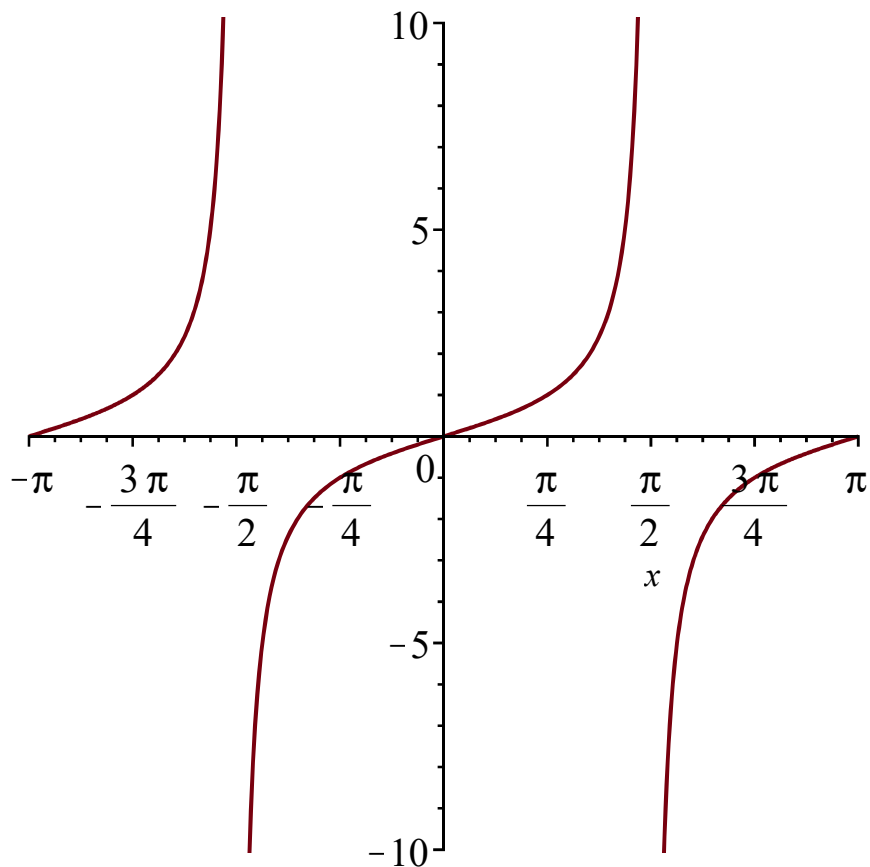
**(d)**

Suppose that  $a$  and  $b$  are two different roots of  $f(x)$ , so  $f(a) = 0$  and  $f(b) = 0$ . As  $x$  moves from  $a$  to  $b$ , the function  $f(x)$  cannot increase all the time (otherwise  $f(b)$  would be greater than  $0$ ) and it cannot decrease all the time (otherwise  $f(b)$  would be less than  $0$ ). It must increase some of the time and decrease some of the time, so there must be some point at which it changes over from increasing to decreasing (or vice-versa), and at that point we will have  $f'(x) = 0$ .

**(e)**

As we see in the plot below, the roots of  $h(x) = \tan(x)$  are at  $x = n\pi$  for integers  $n$ .

```
> plot(tan(x), x=-Pi..Pi, -10..10, discontin=true);
```



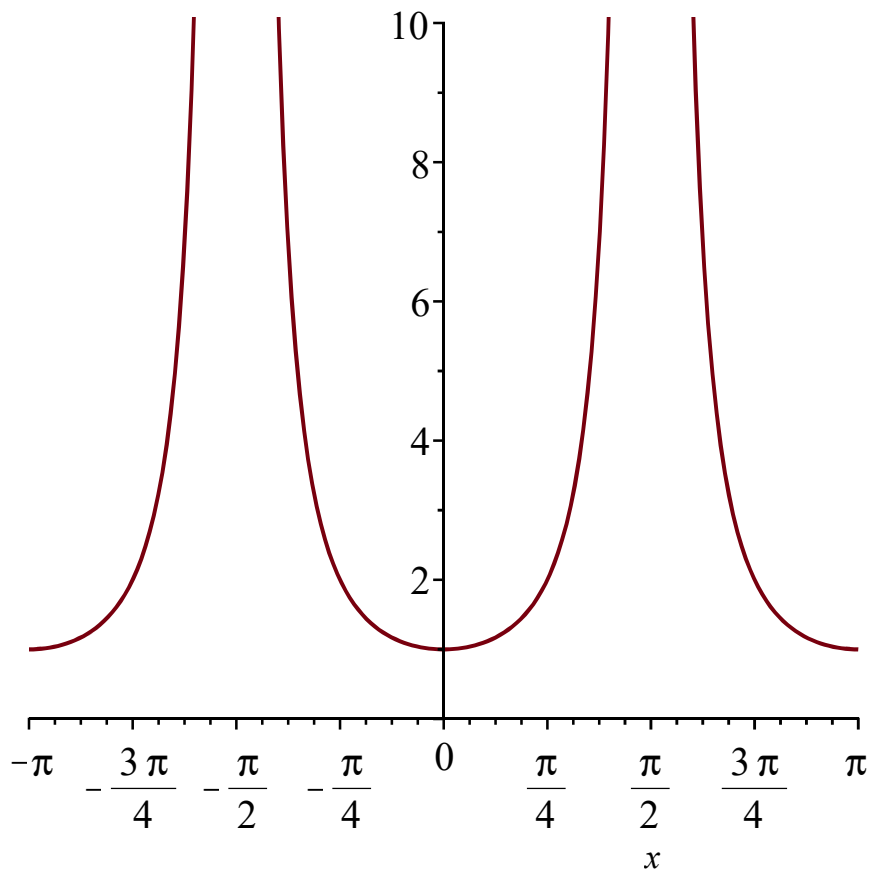
The graph is always sloping upwards, so  $h'(x) > 0$  for all  $x$ . In fact, we have  $h'(x) = \sec(x)^2 = 1 + \tan(x)^2$ , which shows that  $1 \leq h'(x)$  for all  $x$ . In any case,  $h'(x)$  has no roots at all, contradicting Rolle's principle. So what goes wrong in the argument that we outlined? As  $x$  moves from 0 to  $\pi$ , the function increases from 0 up towards  $\infty$ , then jumps down discontinuously. When  $x = \frac{\pi}{2}$ , neither  $h(x)$  nor  $h'(x)$  is really well-defined.

```
> D(tan)(x);
```

$$\tan(x)^2 + 1$$

(16)

```
> plot(D(tan)(x), x=-Pi..Pi, 0..10);
```



### Exercise 3

(a)

Put  $y = x^n$ . Then  $y' = n x^{n-1}$  and  $y'' = n(n-1)x^{n-2}$  and  $y''' = n(n-1)(n-2)x^{n-3}$ . If  $n = 0$  then  $y' = 0$ , so we cannot divide by  $y'$ , so  $S(y)$  is undefined. For any other value of  $n$ , we have  $\frac{y''}{y'}$

$$= \frac{n-1}{x} \text{ and } \frac{y'''}{y'} = \frac{(n-1)(n-2)}{x^2}. \text{ This gives}$$

$$S(y) = \frac{y'''}{y'} - \frac{3 \left( \frac{y''}{y'} \right)^2}{2} = \frac{(n-1)(n-2)}{x^2} - \frac{3 \left( \frac{n-1}{x} \right)^2}{2} = \frac{2(n^2 - 3n + 2) - 3(n-1)^2}{2x^2}$$

$$= \frac{1 - n^2}{2x^2}$$

This is zero for  $n = 1$  or  $n = -1$ .

(b)

```
> S := (y) -> diff(y,x,x,x)/diff(y,x) -
      (3/2)*(diff(y,x,x)/diff(y,x))^2;
```

$$S := y \rightarrow \frac{\frac{\partial^3}{\partial x^3} y}{\frac{\partial}{\partial x} y} - \frac{3}{2} \frac{\left(\frac{\partial^2}{\partial x^2} y\right)^2}{\left(\frac{\partial}{\partial x} y\right)^2} \quad (17)$$

> S(x^n);

$$\frac{\left(\frac{x^n n^3}{x^3} - \frac{3 x^n n^2}{x^3} + \frac{2 x^n n}{x^3}\right) x}{x^n n} - \frac{3 \left(\frac{x^n n^2}{x^2} - \frac{x^n n}{x^2}\right)^2 x^2}{2 (x^n)^2 n^2} \quad (18)$$

> simplify(S(x^n));

$$\frac{-n^2 + 1}{2 x^2} \quad (19)$$

> solve(%=0,n);

$$-1, 1 \quad (20)$$

(c)

> y := (a\*x+b)/(c\*x+d);

$$y := \frac{ax + b}{cx + d} \quad (21)$$

> simplify(diff(y,x));

$$\frac{ad - bc}{(cx + d)^2} \quad (22)$$

> simplify(diff(y,x,x));

$$-\frac{2c(ad - bc)}{(cx + d)^3} \quad (23)$$

> simplify(diff(y,x,x,x));

$$\frac{6c^2(ad - bc)}{(cx + d)^4} \quad (24)$$

> simplify(S(y));

$$0 \quad (25)$$

(d)

> z := (a\*p^x+b)/(c\*p^x+d);

$$z := \frac{ap^x + b}{cp^x + d} \quad (26)$$

> simplify(S(z));

$$-\frac{(6p^{2x}c^2d^2 + p^{4x}c^4 + 4p^{3x}c^3d + 4p^xc^2d^3 + d^4)\ln(p)^2}{2(cp^x + d)^4} \quad (27)$$

> 1/simplify(expand(1/%));



$$-\frac{\ln(p)^2}{2} \quad (28)$$

(e)

> T := (u) -> diff(u,x)^(1/2) \* diff(diff(u,x)^(-1/2),x,x);

$$T := u \rightarrow \sqrt{\frac{\partial}{\partial x} u} \left( \frac{\partial^2}{\partial x^2} \left( \frac{1}{\sqrt{\frac{\partial}{\partial x} u}} \right) \right) \quad (29)$$

Now try some examples:

> w := x^n; simplify([S(w),T(w)]);

$$w := x^n$$

$$\left[ \frac{-n^2 + 1}{2x^2}, \frac{n^2 - 1}{4x^2} \right] \quad (30)$$

> w := sin(x)^2; simplify([S(w),T(w)]);

$$w := \sin(x)^2$$

$$\left[ \frac{-4 \cos(x)^4 + 4 \cos(x)^2 - 3}{2 \sin(x)^2 \cos(x)^2}, \frac{4 \cos(x)^4 - 4 \cos(x)^2 + 3}{4 \sin(x)^2 \cos(x)^2} \right] \quad (31)$$

> w := ln(x); simplify([S(w),T(w)]);

$$w := \ln(x)$$

$$\left[ \frac{1}{2x^2}, -\frac{1}{4x^2} \right] \quad (32)$$

In each case we see that  $T(w) = -\frac{S(w)}{2}$ . In fact, this is true for any  $w$ . This can be shown as follows.

We first use the chain rule to get:

$$\frac{\partial}{\partial x} \left( \frac{\partial}{\partial x} u \right)^{-\frac{1}{2}} = -\frac{1}{2} \left( \frac{\partial}{\partial x} u \right)^{-\frac{3}{2}} \left( \frac{\partial^2}{\partial x^2} u \right)$$

We then differentiate once more, using the product rule and the chain rule, to get

$$\frac{\partial^2}{\partial x^2} \left( \frac{\partial}{\partial x} u \right)^{-\frac{1}{2}} = -\frac{1}{2} \left( -\frac{3}{2} \right) \left( \frac{\partial}{\partial x} u \right)^{-\frac{5}{2}} \left( \frac{\partial^2}{\partial x^2} u \right)^2 - \left( \frac{1}{2} \right) \left( \frac{\partial}{\partial x} u \right)^{-\frac{3}{2}} \left( \frac{\partial^3}{\partial x^3} u \right)$$

We now multiply both sides by  $\sqrt{\frac{\partial}{\partial x} u}$  and simplify to get

$$\sqrt{\frac{\partial}{\partial x} u} \left( \frac{\partial^2}{\partial x^2} \left( \frac{\partial}{\partial x} u \right)^{-\frac{1}{2}} \right) = \left( \frac{3}{4} \right) \left( \frac{\partial}{\partial x} u \right)^{-2} \left( \frac{\partial^2}{\partial x^2} u \right)^2 - \left( \frac{1}{2} \right) \left( \frac{\partial}{\partial x} u \right)^{-1} \left( \frac{\partial^3}{\partial x^3} u \right)$$

or in different notation

$$T(u) = \frac{3 \left( \frac{u''}{u'} \right)^2}{4} - \frac{u'''}{2 u''} = \left( -\frac{1}{2} \right) \left( \frac{u'''}{u'} - \frac{3 \left( \frac{u''}{u'} \right)^2}{2} \right) = -\frac{S(u)}{2}$$

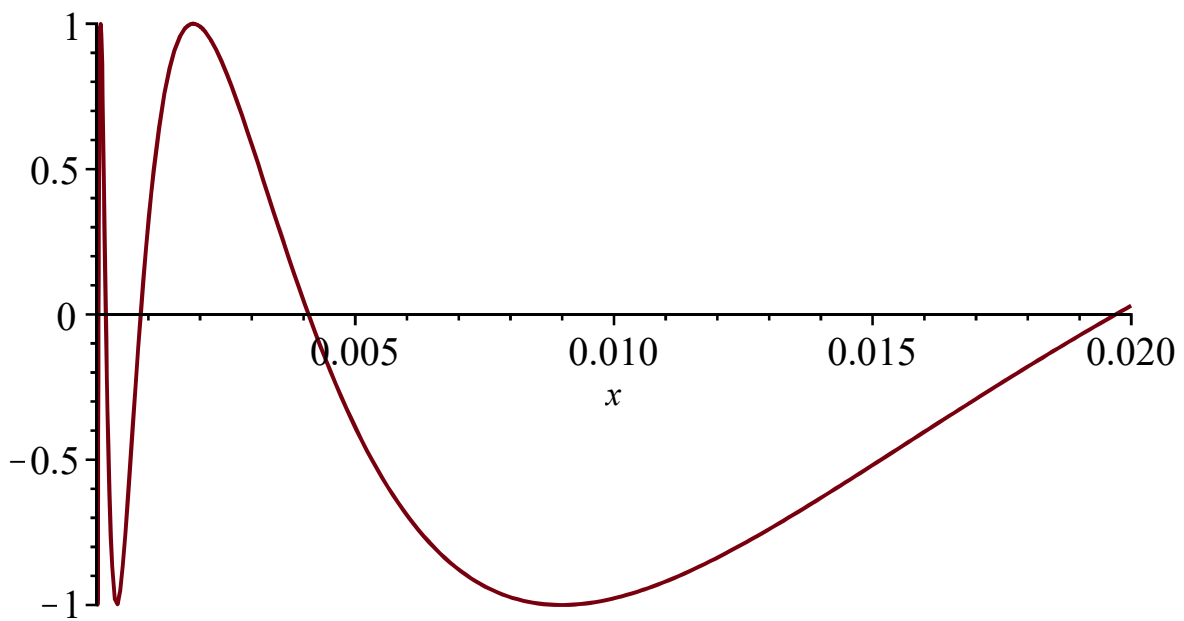
as claimed.

### Exercise 4

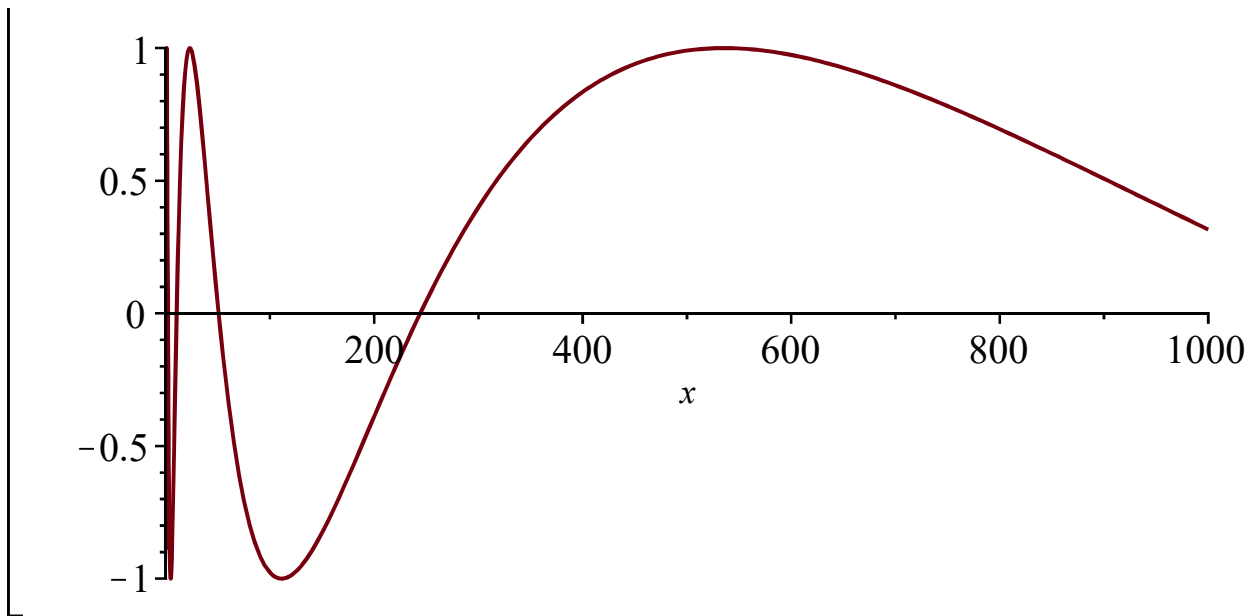
```
> y := cos(-2*ln(x));
```

$y := \cos(2 \ln(x))$  (33)

```
> plot(y, x=0..0.02);
```



```
> plot(y, x=0..1000);
```



```
> a[0] := exp(-Pi/4);
```

$$a_0 := e^{-\frac{\pi}{4}} \quad (34)$$

Here is the general formula for the derivative of  $f(x)$ :

```
> diff(y,x);
```

$$-\frac{2 \sin(2 \ln(x))}{x} \quad (35)$$

We can find the gradient at  $x = a_0$  using the `subs( )` command:

```
> m[0] := subs(x=a[0],diff(y,x));
```

$$m_0 := -\frac{2 \sin\left(2 \ln\left(e^{-\frac{\pi}{4}}\right)\right)}{e^{-\frac{\pi}{4}}} \quad (36)$$

However, it looks better if we simplify this:

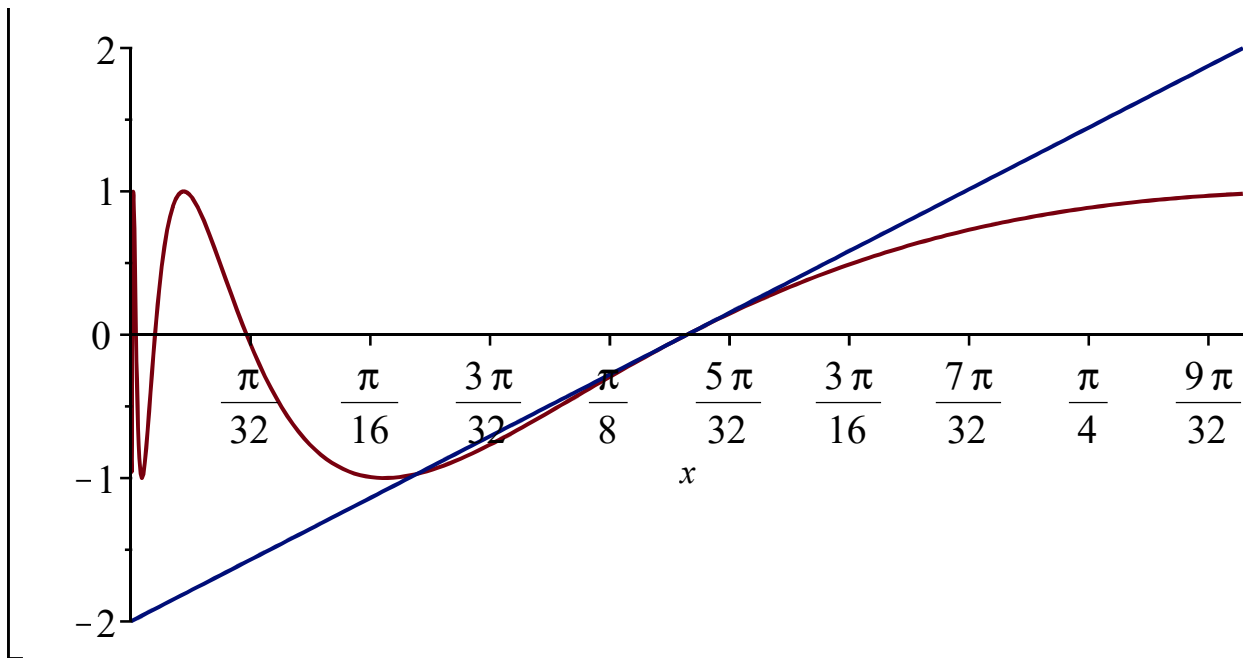
```
> m[0] := simplify(subs(x=a[0],diff(y,x)));
```

$$m_0 := 2 e^{\frac{\pi}{4}} \quad (37)$$

The equation of the line of slope  $m_0$  passing through  $[a_0, 0]$  is just  $y = m_0 (x - a_0)$ .

We can plot this together with  $y$  as follows:

```
> plot([y,m[0]*(x-a[0])],x=0 .. 2*a[0]);
```



To find the other roots, note that  $\cos(t) = 0$  precisely when  $t$  has the form  $\left(k - \frac{1}{2}\right) \text{Pi}$  for some integer  $k$ .

Thus, we have  $y = \cos(-2 \ln(x)) = 0$  precisely when  $-2 \ln(x) = \left(k - \frac{1}{2}\right) \text{Pi}$ , so

$$\ln(x) = \left(\frac{1}{4} - \frac{k}{2}\right) \text{Pi},$$

so  $x = e^{\left(\frac{1}{4} - \frac{k}{2}\right) \text{Pi}}$ . We write  $a_k$  for this root.

The steps that we did for  $a_0$  can be repeated for  $a_3$  as shown below. Then to do  $a_4$  (for example) just change the 3 to 4 and press ENTER four times.

```
> k := 3;
```

$$k := 3$$

(38)

```
> a[k] := exp((1/4-k/2)*Pi);
```

$$a_3 := e^{-\frac{5\pi}{4}}$$

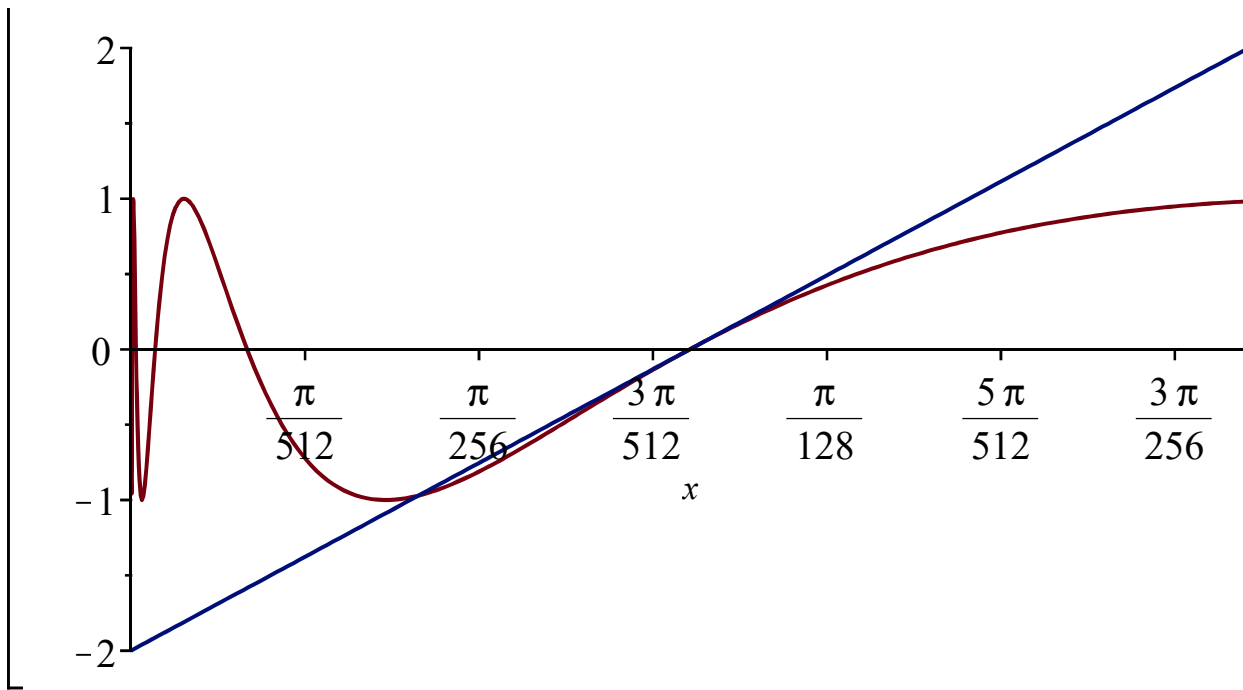
(39)

```
> m[k] := simplify(subs(x=a[k],diff(y,x)));
```

$$m_3 := 2e^{\frac{5\pi}{4}}$$

(40)

```
> plot([y,m[k]*(x-a[k])],x=0 .. 2*a[k]);
```



We find that the tangent lines always meet the  $y$ -axis at  $y=2$  or  $y=-2$ . This is not too hard to see directly.

In general we have  $\frac{dy}{dx} = -\frac{2 \sin(2 \ln(x))}{x}$ . When  $x = a_k$  we have  $2 \ln(x) = \left(\frac{1}{2} - k\right) \pi$  and so  $\sin(2 \ln(x)) = (-1)^k$ , so  $m_k = \frac{2 (-1)^{k+1}}{a_k}$ . The line  $L_k$  has equation  $y = m_k (x - a_k)$  so the intercept at  $x=0$  is  $-m_k a_k$ , which is  $2 (-1)^k$ .